



# YOUNG RESEARCHERS WORKSHOP

## GPCE 2004

Berkeley  
University of California

# Generative Tools for Hybrid Systems

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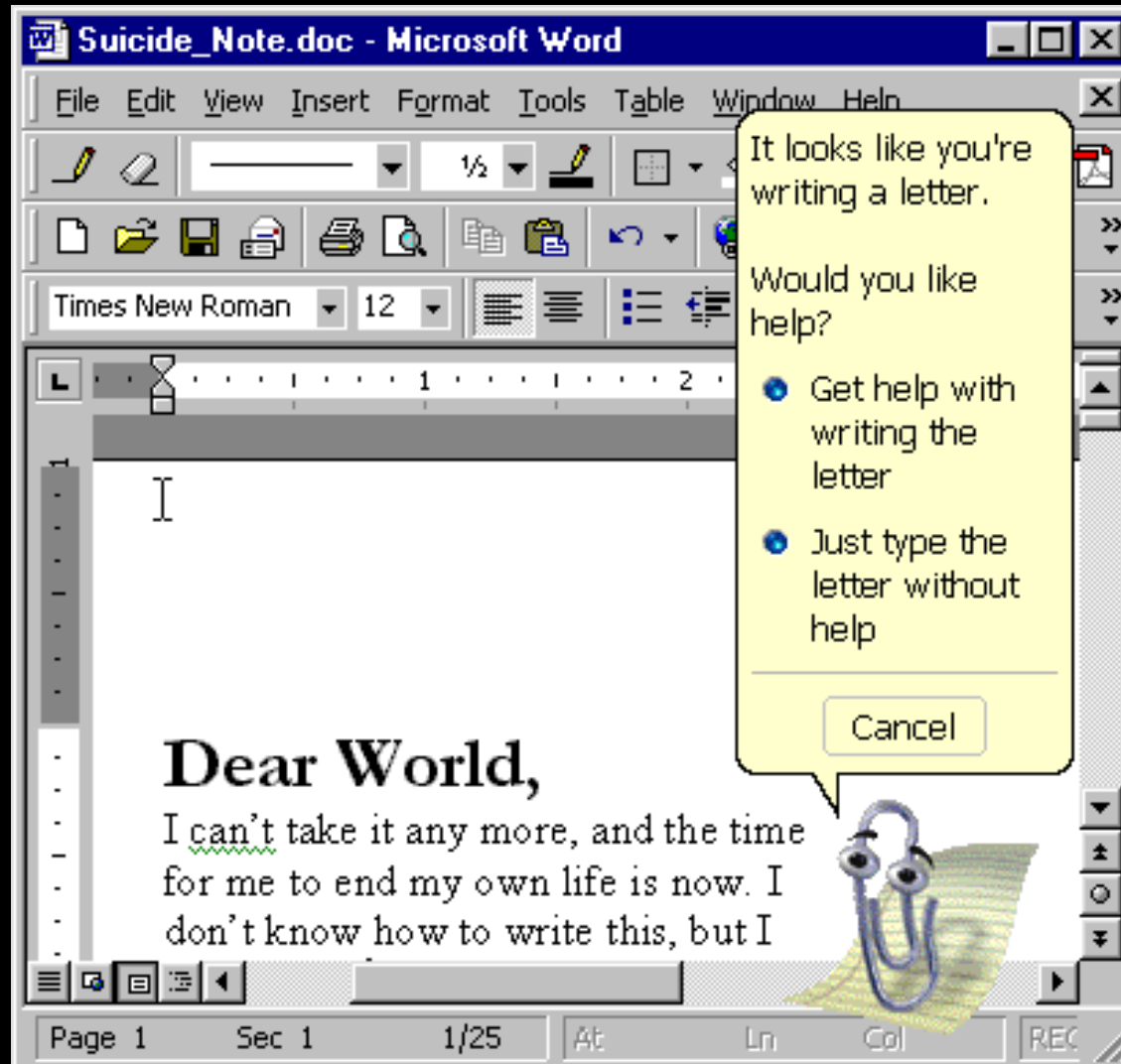
# Overview

- Introduction
- Motivation
- Backgrounds
  - Domain-Specific Modeling
  - Hybrid Systems
- What has been done
- Looking forward
- Conclusions





# “Help”





# Writer's Block

- What is more daunting than a blank page, and an unfamiliar task (language, topic, program, etc.)
- How can you assimilate bits of pieces of information (stored in your head, distributed throughout your design/idea, and informally stated at best) into a coherent concept understandable to your end audience?





# Mythbusters!

The myth that some people come away believing, when exposed to the notion of a formal language, is that a “formal language” is a formal-looking language; that any language that contains lots of Greek letters and mathematical symbols is formal.

— *David Harel, Bernard Rumpe, “Syntax, Semantics, and all that Stuff”*



# Why Model Domains?

- Domain modeling can be
  - Formal
  - Intuitive
  - *Useful*



*Do you know what the funny thing is about domain modeling? It's the little differences.*



# Example(s)

- PowerPoint
  - Domain: Visual Presentation
- Excel
  - Domain: Accounting/number crunching
- MATLAB
  - Domain: Discrete systems
- L<sup>A</sup>T<sub>E</sub>X
  - Domain: Typesetting (sub: Academic papers, books, posters...)
- Problems:
  - *How long does it take to create one of these environments???*
  - *What happens if you try to use one of these environments for something it was not intended???*
  - *What about creating domains for non-traditional systems???*



# Creating Domain-Specific Modeling Environments (DSMEs)

- A *working* application for system design
- A *customized* modeling environment which is a *restricted* input layer that enforces some meaning
- An implementation *reflecting* a domain's familiar and consistent
  - methodologies
  - notation
  - semantics
- An *efficient* user interface







# Hybrid Systems

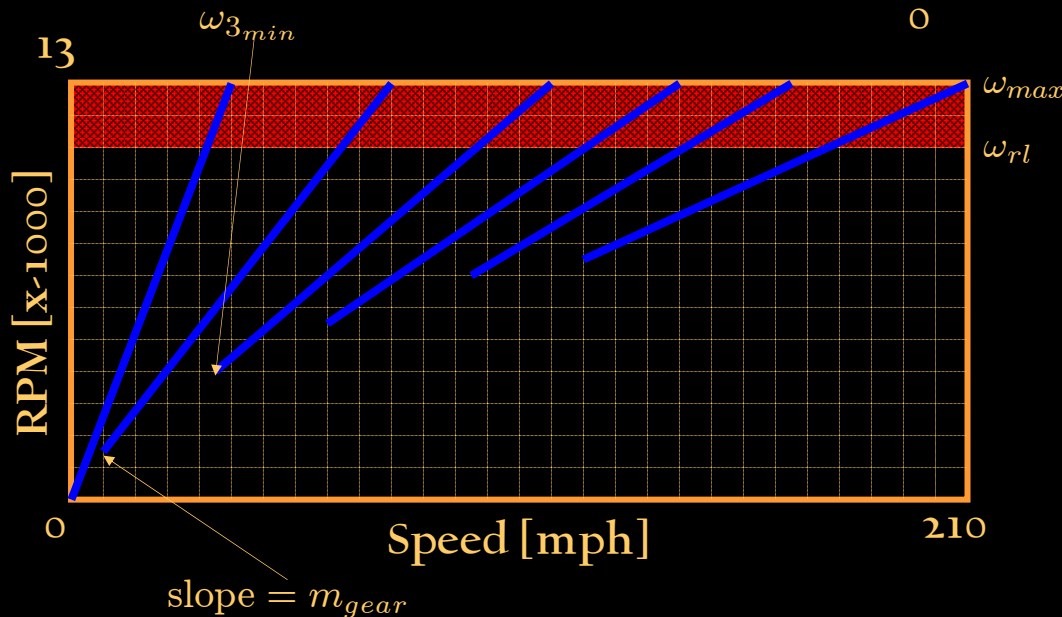
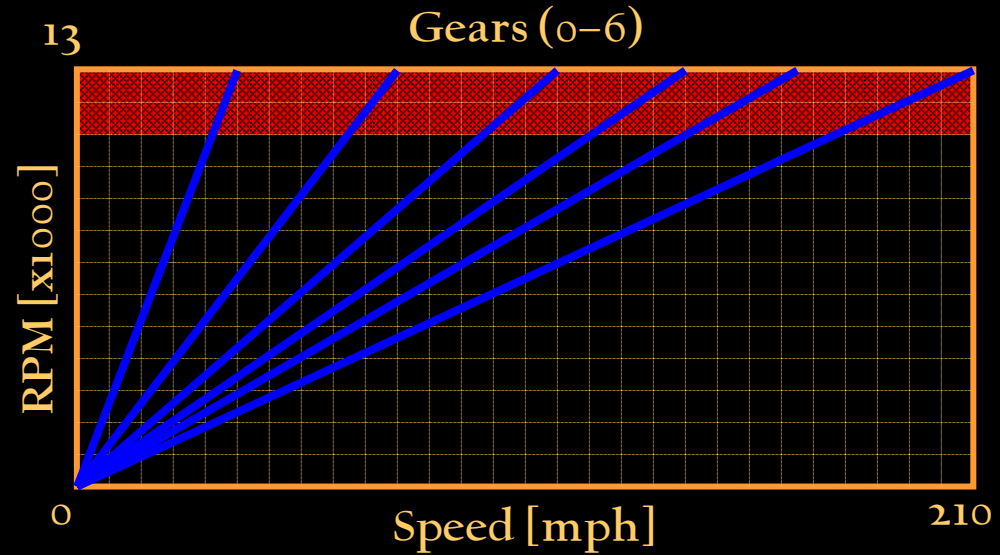
- An emerging, complex, engineering discipline
- Systems that are described both by
  - Discrete states of operation (e.g., modes)
  - Continuous dynamics within each discrete state



# Example Hybrid System

## Automobile velocity

- Shifting gears allows higher speeds before damaging engine (a.k.a. "redlining")
- However, not all gears function well at low RPM, requiring a certain speed before their use

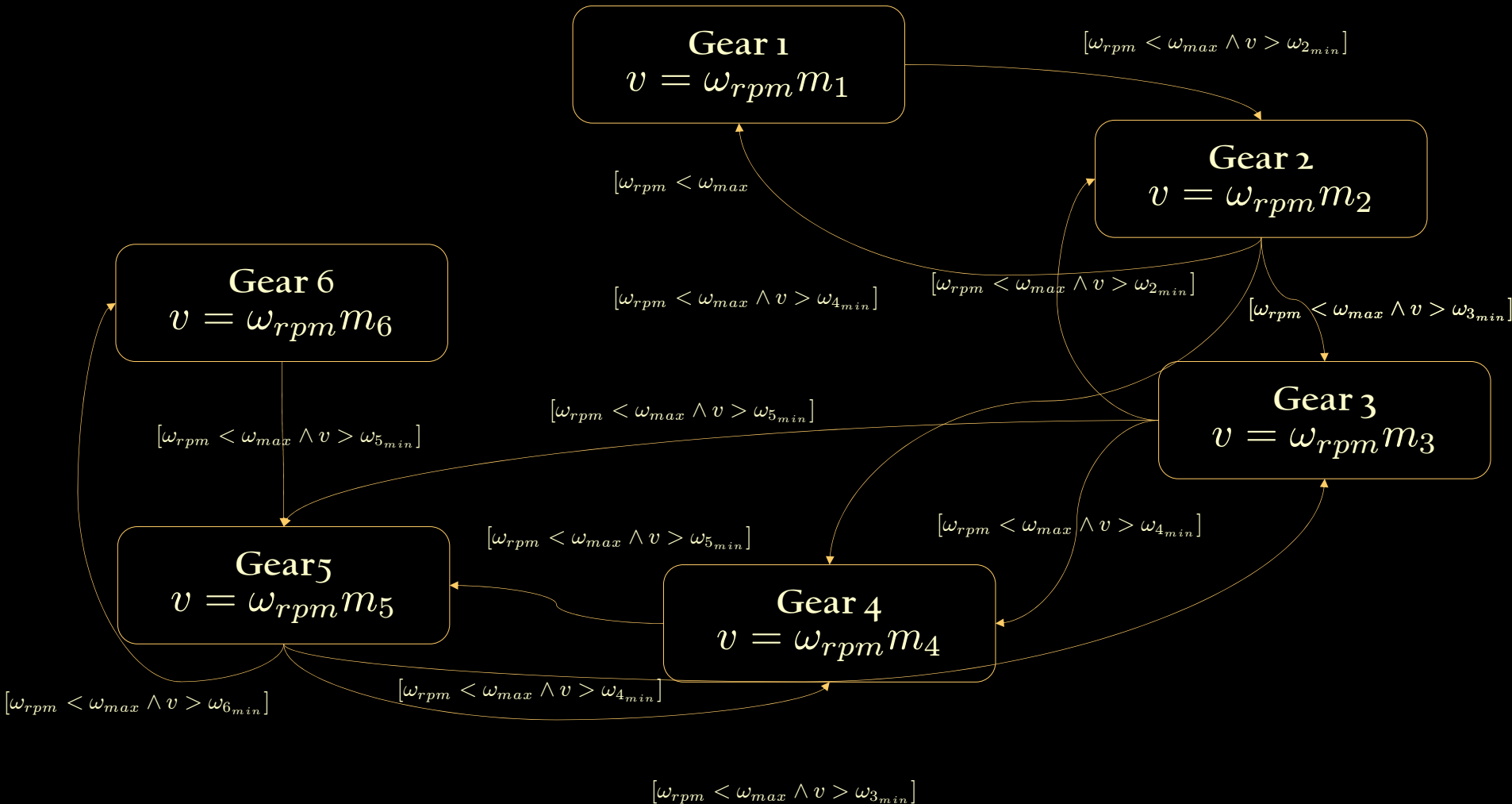


## Constrained gearbox

- "Safe" zones for each gear
- Limited shifting, due to safe zones
- Requires a smart controller for automatic transmissions

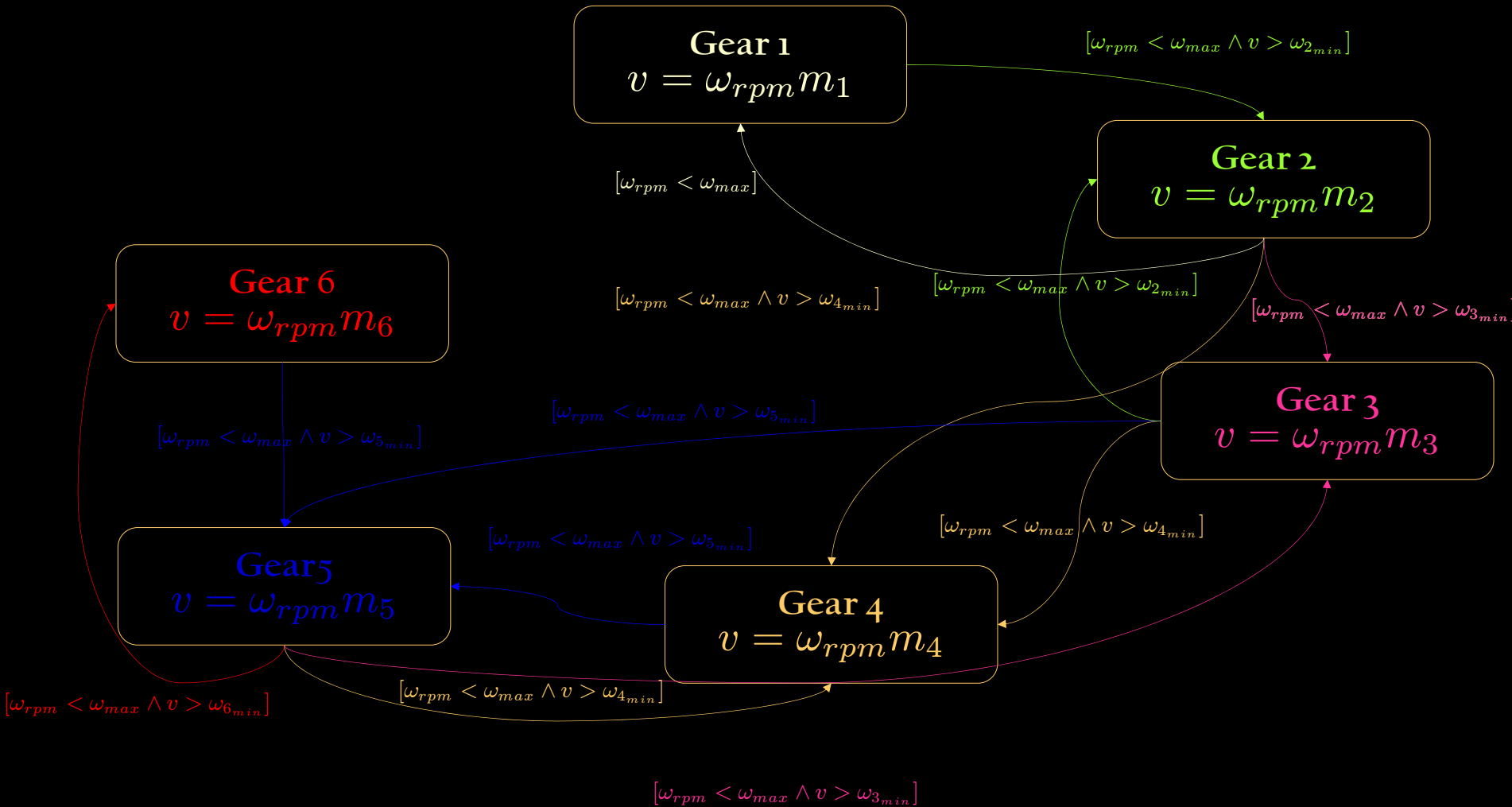


# Mathematical Specification of Transmission System





# Mathematical Specification of Transmission System





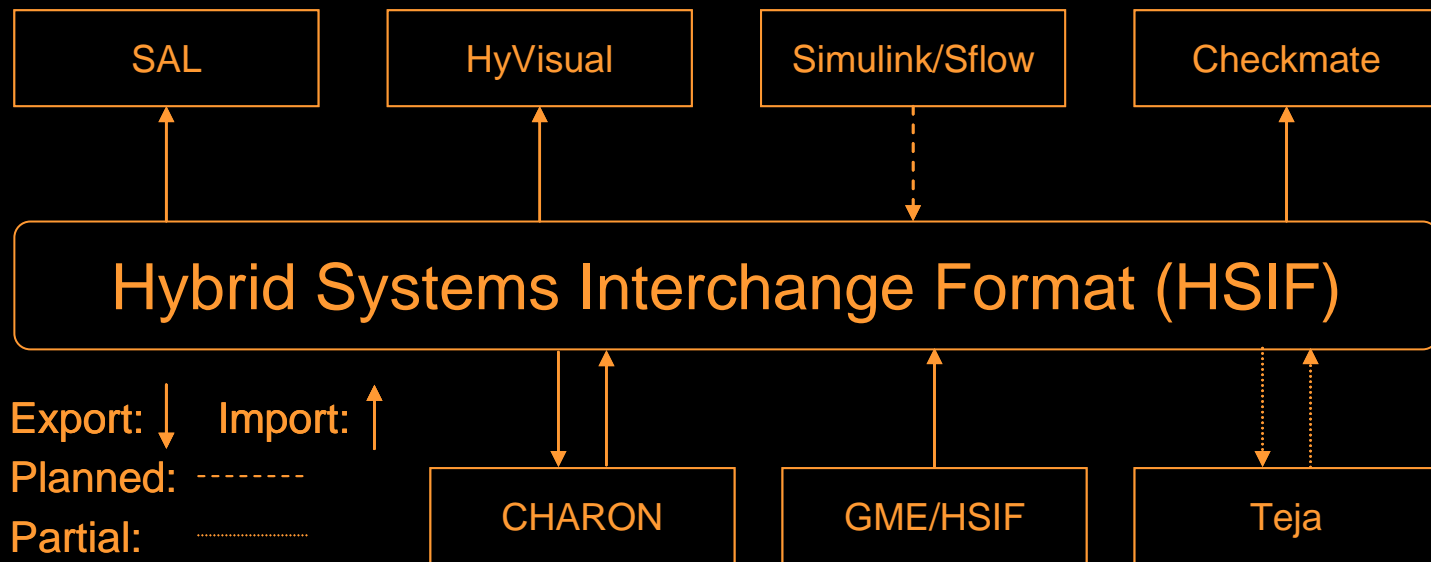
# Hybrid Systems Tools

- Modeling
  - Describe the system, its constraints, some portions of the controller
- Controller synthesis
  - Generate switching criteria, guards, etc., based on constraints
- Verification/Validation
  - Assert or contradict that the controller satisfies the constraints
- Code generation
  - Actually implement the controller in an embedded system
- No one tool can do all of this?
  - So, what about interchanging models between tools?



# HSIF

- The Hybrid Systems Interchange Format (HSIF) was designed to satisfy the first portion (system spec.)





# HSIF Modeling Language

- As a graduate student, I created the HSIF Modeling Environment (HSIF-ME)
  - a domain-specific graphical modeling tool for the hybrid systems community
  - specification very similar to mathematical definition (as proposed by Lygeros, Simic, et al.)
  - generated several formats, for the tools that provided their syntax and semantics
  - easier to use than the specialized verification/validation simulation tools (for the most part)
- A very lightweight tool (can exist without any other components) for system description



# HSIF Problems

- Design by committee
  - Too many tool-specific syntax entries
  - Unclear semantics for some syntaxes
- Many people wanted to be involved, few wanted to put up the work to match their rhetoric 😊
  - Resulted in me doing all the work
  - This is why so many routes are “planned”





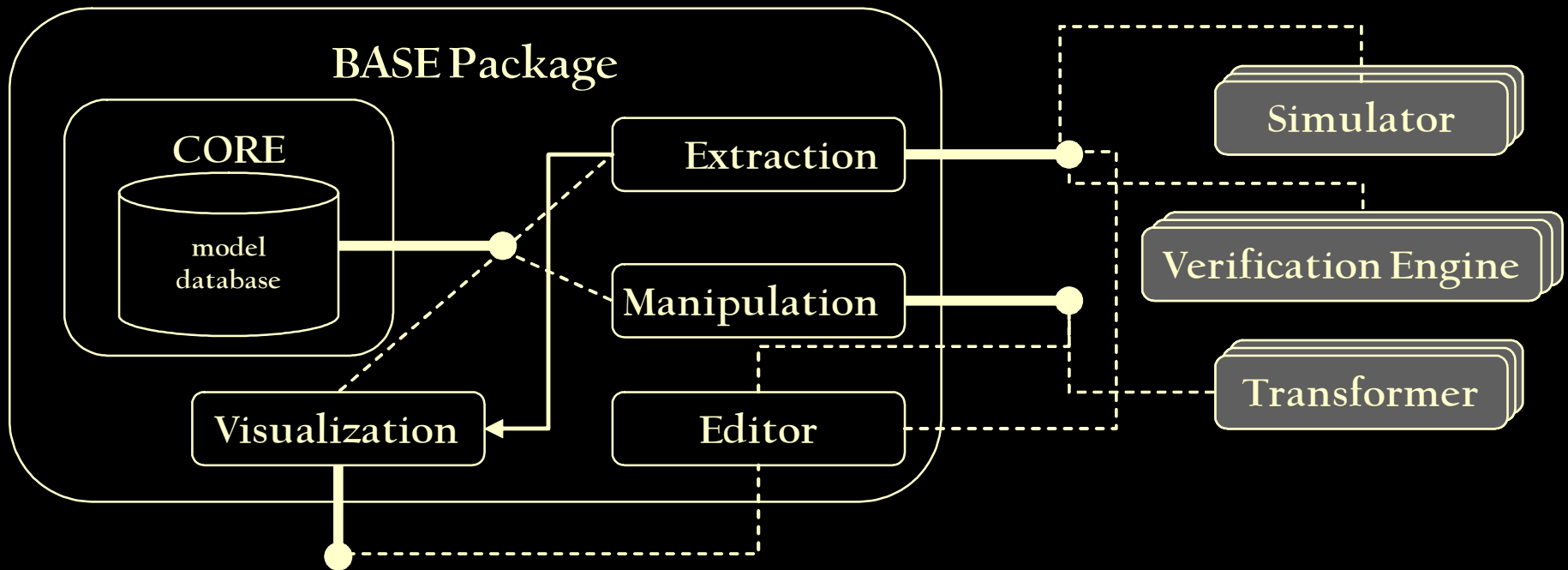
# Looking forward...

- How to address these problems:
  - Design by committee, unintuitive syntaxes, semantic interchange issues
- How to maintain these goals:
  - Intuitive modeling interface, tool interoperability
- How to improve basic tasks
  - Utilize state-of-the-art simulators, provide error bounds on event detection
- How to take advantage of emerging applications
  - BioSPICE, pursuit/evasion games, reachability calculations, space vehicle control (NASA H&RT)



# Research Proposal

- A self contained facility, which can interchange components with more sophisticated tools





# Scientific details

- How can we specify the semantics of the component interfaces?
  - Can the approach of IDL be taken, but abstract equation solving techniques rather than language/OS impl?
- What does it mean to deploy a totally abstract system?
  - Can we ship a version that will interchange with Matlab, as well as Mathematica, as well as a standalone C++ app, and dependably interact with the same models?
- How should we manage semantic interoperability?
  - Can we accept some mismatch in execution styles, and if so, how much mismatch results in incorrect roundtripping or incorrect execution strings?



# Technical Details

- What language should we choose for implementation?
  - Python, Java, run on many platforms, not so fast (although with JNI maybe faster)
- Can we accept certain platform requirements for certain components (e.g., verifiers may work only in Linux for some components)



# Why is tool interoperation hard?

- Hybrid systems tools share a common ontology
  - Hybrid Automata
  - Events and Transitions
  - Equations
- Common semantics with similar ontology
  - Flow vs. Differential equations
  - Discrete States vs. Locations
- Discrepant semantics with similar/common ontology
  - Global and local variable precedence
  - Model of computation discrepancies

Tool A || Tool B

$A == A$

$\text{sem}(B) == \text{sem}(\beta)$

$\text{sem}(C) != \text{sem}(C)$



# What steps are underway?

- Weekly discussion with leading experts at Berkeley
  - Shankar Sastry, Edward Lee, Tom Henzinger, and their students
- Interactions with previous participants
  - Vanderbilt, Penn, agree with need for new revisions
- Collaboration with industry to determine goals/constraints
  - Ford, GM, both require Matlab/Simulink interoperability for existing models



# Conclusions

- Current state of the art is lightweight tool-abstracted interface format
- Desired research tool is similarly lightweight, but abstracted more by semantic requirements than desired working tools
- Tools still drive the nature of execution and development, but the research topics (especially biological ones) promise to provide required funding for the tool development



# Questions?



"Well HAL, I'm damned if I can find anything wrong with it."

"Yes. It's puzzling. I don't think I've ever seen anything quite like this before."

-- *2001: A Space Odyssey*