## ECE 304: Fall '02 Final Exam Solutions

## Problem 1



Figure 1
Circuit for problem 1; $\mathrm{R}_{\mathrm{S}}=1 \mathrm{k} \Omega, \mathrm{R}_{\mathrm{C}}=1 \mathrm{k} \Omega, \mathrm{C}_{\mathrm{u} 1}=\mathrm{C}_{\mathrm{u} 2}=5 \mathrm{pF}$, and $\mathrm{C}_{\mathrm{p} 11}=\mathrm{C}_{\mathrm{p} i 2}=100 \mathrm{pF}$

| NAME | Q_Q2 <br> MODEL | Q_Q1 <br> Qn |
| :--- | :---: | :---: |
| IB | $9.80 \mathrm{E}-05$ | $9.90 \mathrm{E}-05$ |
| IC | $9.80 \mathrm{E}-03$ | $9.90 \mathrm{E}-03$ |
| VBE | $7.14 \mathrm{E}-01$ | $7.14 \mathrm{E}-01$ |
| VBC | $-5.20 \mathrm{E}+00$ | $-4.09 \mathrm{E}+00$ |
| VCE | $5.91 \mathrm{E}+00$ | $4.80 \mathrm{E}+00$ |
| BETADC | $1.00 \mathrm{E}+02$ | $1.00 \mathrm{E}+02$ |
| GM | $3.79 \mathrm{E}-01$ | $3.83 \mathrm{E}-01$ |
| RPI | $2.64 \mathrm{E}+02$ | $2.61 \mathrm{E}+02$ |
| RX | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| RO | $1.00 \mathrm{E}+12$ | $1.00 \mathrm{E}+12$ |
| CBE | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| CBC | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| CJS | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| BETAAC | $1.00 \mathrm{E}+02$ | $1.00 \mathrm{E}+02$ |
| CBX/CBX2 | $0.00 \mathrm{E}+00$ | $0.00 \mathrm{E}+00$ |
| FT/FT2 | $6.03 \mathrm{E}+18$ | $6.09 \mathrm{E}+18$ |

Figure 2
Q-point data for Figure 1; $C_{B E}$ and $C_{B C}$ are zero, $r_{O}=10^{12} \Omega$

The load capacitance $C_{L}$ represents the high-frequency input capacitance of the following stage. ${ }^{1}$ Note that the emodel statement of Q1 and Q2 includes no capacitances, so $\mathrm{C}_{\mu}$ and $\mathrm{C}_{\pi}$ are given instead by the external capacitors $\mathrm{C}_{\mathrm{u} 1}=\mathrm{C}_{\mathrm{u} 2}=\mathrm{C}_{\mu}=5 \mathrm{pF}$ and $\mathrm{C}_{\mathrm{pi1}}=\mathrm{C}_{\mathrm{pi2}}=\mathrm{C}_{\pi}=100 \mathrm{pF}$.

Using the circuit of Figure 1 and the Q-point data of Figure 2, answer the following questions. Marks are apportioned according to difficulty, with part 6 counting the most.

1. What is this circuit named? Cascode
2. What is the usefulness of this circuit? High gain and wide bandwidth with good impedance match for Thevenin driver
3. How is the usefulness of this circuit achieved? The CB output stage provides high gain and also high bandwidth because $C_{\mu}$ is grounded on base side leading to a short time constant for the CB stage. The CE input stage serves to convert the driver to a high impedance Norton current source that matches well to the CB stage. The CB stage presents such a low impedance to the CE stage that the CE stage has a gain of about $2 \mathrm{~V} / \mathrm{V}$, so the Miller effect in the CE stage is unimportant in limiting the bandwidth of the circuit.
4. Find the Norton equivalent of the combined voltage driver and first stage at midband.

We make a small-signal equivalent of the first stage, and map that into a small-signal Norton equivalent. Ignore $R_{B}$, which is too large to make much difference.


Figure 3
Norton equivalent
5. Find the input impedance of the second stage at midband.

We construct the small-signal equivalent of the output stage and put a test voltage at the input.


Figure 4
Input resistance is $2.612 \Omega=r_{\pi} /\left(\beta_{a c}+1\right)$

[^0]6. Using the open-circuit time constant method, estimate the value of the load capacitance $C_{L}$ that results in a corner frequency of 4 MHz .
We find the resistances seen by each capacitor, determine the RC time constants, and add them up to find the total time $\tau$. Then $f_{C}=1 /(2 \pi \tau)$. Again, ignore $R_{B}$, as it is too large to matter.


Figure 5
For $C_{\mu 2}$ and $C_{L}, R=R_{C}=1 k \Omega$


Figure 6


Figure 7
For $\mathrm{C}_{\pi 1}, \mathrm{R}=\mathrm{r}_{\pi 1} / / \mathrm{R}_{\mathrm{s}}=207 \Omega$


Figure 8

$$
\text { For } C_{\mu 1}, R=r_{e 2}+r_{\pi 1} / / R_{s}+g_{m 1} r_{e 1}\left(r_{r} 1 / / R_{s}\right)=209.7+207.0=416.7 \Omega
$$

Total time $\tau=5 p F(416.7+1 k)+100 p F(207+2.6)+C_{L} 1 k=28.04 n s+C_{L} 1 k$
For a corner of 4 MHz , require $\tau=1 /(2 \pi 4 M)=39.79 \mathrm{~ns}=C_{L} 1 \mathrm{k}+28.04 \mathrm{~ns} \rightarrow C_{L}=11.75 \mathrm{~ns} / 1 \mathrm{k}$ $=11.75 \mathrm{pF}$.
7. Do you expect your estimate for $C_{\llcorner }$to be accurate, or too low, or too high? Explain your answer.
The open-circuit method assumes all capacitors are open circuits but the one selected. If in fact some of these capacitors are short-circuits (or, at any rate, not open-circuits), the resistance actually seen by the selected capacitor will be lower than the open-circuit estimate, and the true time constant will be shorter. Therefore, we expect the time constant estimated by the opencircuit method to be an upper bound, and the subtracted amount 28.04 ns to be an upper bound. If the subtracted amount really is lower, $C_{L}$ in fact will be larger. So we expect $C_{L}=11.75$ ns is a lower bound.

## Problem 2



Figure 9
Inventory of parts for problem 2; only one of the two signal sources is used
Figure 9 shows two possible signal sources, a T-section feedback network and a voltage amplifier. By following the steps listed below, hook up these parts to make a transresistance amplifier with negative feedback and an overall gain with feedback of 100 V/A.
8. Determine the simplest T-section

We are told that this is a transR amplifier, that is, voltage out and current in. Therefore, $\beta_{F B}=I / \mathrm{V}$ $=$ VCCS. Therefore, we find the two-port with a VCCS on the left (feedback) side. We find $\beta_{F B}$
$=-\left[R_{C} /\left(R_{C}+R_{A}\right)\right] /\left(R_{B}+R_{A} / / R_{C}\right)$. If we let $R_{B} \rightarrow 0, \beta_{F B}=--1 / R_{A}$. Therefore, we need only $R_{A}$ to control $\beta_{F B}$, and can let $R_{C} \rightarrow \infty$.
9. Sketch the circuit with the simplified T-section and the appropriate signal source


Figure 10
Circuit with simplified two-port
10. Show how to determine whether you have negative feedback


Figure 11
Positive test voltage at input shows negative return voltage on input $R_{I} \rightarrow$ negative feedback
11. Find the resistor values for the T -section assuming no loading

For no loading, the closed loop gain is $1 / \beta_{F B}=R_{A}=100 \mathrm{~V} / \mathrm{A} \rightarrow R_{A}=100 \Omega$
12. Find the loaded gain with feedback

The loaded gain with feedback is found using the two-port representation of the feedback network and setting $\beta_{F B}=0$.


Figure 12
Two-port representation of feedback network

Inserting the feedback network, we find $R_{A} / / R_{/} / / R_{S}$ at the input and $R_{O}+R_{A}$ at the output.
Consequently the input voltage is $V_{I}=I_{S}\left(R_{A} / / R_{/} / / R_{S}\right)$ and the output voltage is
$V_{O}=A_{v} V_{I} R_{A} /\left(R_{A}+R_{O}\right)=I_{S}\left(R_{A} / / R_{l} / / R_{S}\right) A_{v} R_{A} /\left(R_{A}+R_{O}\right) \rightarrow V_{O} / I_{S}=\left(R_{A} / / R_{l} / / R_{S}\right) A_{v} R_{A} /\left(R_{A}+R_{O}\right)$.
The loaded gain with feedback is then

$$
\begin{aligned}
A_{v}(F B) & =\left(\mathrm{R}_{\mathrm{A}} / / \mathrm{R}_{\mathrm{l}} / / \mathrm{R}_{\mathrm{S}}\right) \mathrm{A}_{v} \mathrm{R}_{\mathrm{A}} /\left(\mathrm{R}_{\mathrm{A}}+\mathrm{R}_{\mathrm{O}}\right) /\left\{1+\beta_{\mathrm{FB}}\left(\mathrm{R}_{\mathrm{A}} / / \mathrm{R}_{\mathrm{l}} / / \mathrm{R}_{\mathrm{S}}\right) \mathrm{A}_{v} \mathrm{R}_{\mathrm{A}} /\left(\mathrm{R}_{\mathrm{A}}+\mathrm{R}_{\mathrm{O}}\right)\right\} \\
& =\left(\mathrm{R}_{\mathrm{A}} / / \mathrm{R}_{\mathrm{l}} / / \mathrm{R}_{\mathrm{S}}\right) \mathrm{A}_{v} \mathrm{R}_{\mathrm{A}} /\left(\mathrm{R}_{\mathrm{A}}+\mathrm{R}_{\mathrm{O}}\right) /\left\{1+\left(\mathrm{R}_{\mathrm{A}} / / \mathrm{R}_{\mathrm{J}} / / \mathrm{R}_{\mathrm{S}}\right) \mathrm{A}_{v} /\left(\mathrm{R}_{\mathrm{A}}+\mathrm{R}_{\mathrm{O}}\right)\right\}
\end{aligned}
$$

Problem 3


Stage 2


Figure 13
Three-stage amplifier for Problem 3
Using the three-stage amplifier of Figure 13, do the following.

1. Find formulas for the pole frequencies $f_{1}, f_{2}, \ldots$ in Hz using the open-circuit time-constant method


Figure 14
For $C_{F}, R=0.998 G \Omega ; f_{1}=1 /\left(2 \pi R C_{F}\right)=1 /\left(2 \pi 0.998 \times 3.183 \times 10^{9-12}\right)=50.1 \mathrm{~Hz}$.
$R=R_{01}+\left(1-A_{v}\right)\left(R_{S} / / R_{I}\right)=10 k+1 E 8 * 9.99=9.99 E 8$; PSPICE does not satisfy KCL. Error is negligible.


Figure 15
For $\mathrm{C}_{2}, \mathrm{R}=\mathrm{R}_{\mathrm{O}}=10 \mathrm{k} \Omega ; \mathrm{f}_{2}=1 /\left(2 \pi \mathrm{C}_{2} \mathrm{R}\right)=1 /(2 \pi \times 31.831 \mathrm{p} \times 10 \mathrm{k})=500 \mathrm{kHz}$


Figure 16
For $\mathrm{C}_{3}, \mathrm{R}=\mathrm{R}_{\mathrm{O}}=10 \mathrm{k} \Omega, \mathrm{f}_{3}=1 /\left(2 \pi \mathrm{C}_{3} \mathrm{R}_{\mathrm{O}}\right)=1 /(2 \pi 6.366 \mathrm{pF} \times 10 \mathrm{k})=2.5 \mathrm{MHz}$
2. Find a formula for the voltage gain $\mathrm{V}_{\text {Out }} / \mathrm{V}_{\mathrm{S}}$ at zero frequency (DC)


Figure 17
Voltage gain at zero frequency
Gain $=A_{v 3} A_{v 2} A_{v 1} R_{l} /\left(R_{I}+R_{S}\right)=10^{8} \times 10^{4} /\left(1+10^{4}\right)=99.99 \times 10^{6} \mathrm{~V} / \mathrm{V}$
3. Find a formula for the voltage gain including frequency dependence and put it in standard form as a product of zeros, high-pass and low-pass factors in standard form. Use the notation $\mathrm{f}_{1}, \mathrm{f}_{2}, \ldots$ for the pole frequencies in Hz

$$
\text { Gain }=A_{v 3} A_{v 2} A_{v 1} R_{l} /\left(R_{l}+R_{S}\right) \times\left\{\left(1+j f / f_{1}\right)\left(1+j f / f_{2}\right)\left(1+j f / f_{3}\right)\right\}^{-1}
$$

4. Make Bode phase and dB magnitude plots for the case in Figure 18 with gains given by $A_{v 1}=$ $-10^{8} \mathrm{~V} / \mathrm{V}, \mathrm{A}_{v 2}=-1 \mathrm{~V} / \mathrm{V}, \mathrm{A}_{v 3}=1 \mathrm{~V} / \mathrm{V}$. Label all corners (frequency and value) and slopes. On both plots indicate the number of decades in frequency between breaks in the curves. Use numerical values in Hz for frequencies, not radians.

$$
\begin{aligned}
& \text { PARAMETERS: } \\
& \hline \mathrm{CF}=3.183 \mathrm{pF} \\
& \mathrm{C} 2=31.831 \mathrm{pF} \\
& \mathrm{C} 3=6.366 \mathrm{pF} \\
& \mathrm{RO} 1=10 \mathrm{k} \\
& \mathrm{RO} 2=10 \mathrm{k} \\
& \mathrm{RO} 3=10 \mathrm{k} \\
& \mathrm{RS}=10 \\
& \mathrm{RI} 1=10 \mathrm{k}
\end{aligned}
$$

Figure 18


Figure 19
Bode magnitude plot


Figure 20
Bode phase plot - approximation of widely spaced poles would make $\phi(500 \mathrm{kHz})=$ $-135^{\circ}$ and $\phi(2.5 \mathrm{MHz})=-225^{\circ}$
5. Assuming this amplifier is used to make a feedback voltage amplifier, find the maximum value of feedback $\beta_{\mathrm{FB}}$ in units of $\mathrm{V} / \mathrm{V}$ that allows a $45^{\circ}$ phase margin
For a phase margin of $45^{\circ}, \phi=-135^{\circ}$. Using Bode plots assuming widely spaced poles, we'd expect $-135^{\circ}$ at location of second pole, setting $f_{135}=500 \mathrm{kHz}$. At this frequency the Bode gain plot shows $A_{\nu}=80 \mathrm{~dB}=10^{4} \mathrm{~V} / \mathrm{V} \rightarrow \beta_{F B}=1 / 10^{4}=10^{-4} \mathrm{~V} / \mathrm{V}$
6. Assuming the approximation of widely spaced poles, describe a method to select $\mathrm{C}_{\mathrm{F}}$ so the phase margin of a feedback voltage amplifier based on Part 4 is $45^{\circ}$ at a specified value of $\beta_{\text {FB }}$.
Method: Draw line on Bode magnitude plot at 1/ $\beta_{F B}$ and find point on this curve corresponding to location of second pole. Draw a line at $20 \mathrm{~dB} / \mathrm{decade}$ backward from this point to the zero frequency gain value. This intersection is the new pole frequency. Find ratio ' $r$ ' of original frequency of lowest pole to this new frequency; $r=f_{O R I G} / f_{N E W}$. This is the ratio of the new capacitance value to the original capacitance value. Then $C_{N E W}=C_{\text {ORIG }} \times r$.
7. Using the method of Part 6 , for the amplifier of Part 4 show your calculation of the value for $C_{F}$ for a $45^{\circ}$ phase margin with $\beta_{F B}=10^{-2} \mathrm{~V} / \mathrm{V}$.
Value of $1 / \beta_{F B}=100 \rightarrow 40 \mathrm{~dB}$. This value is 120 dB down from zero f gain. At $20 \mathrm{~dB} / \mathrm{dec}$, it takes 6 dec to rise to zero f gain of 160 dB , so new lowest pole has to be $f_{P 2} / 10^{6}=500 \mathrm{k} / 10^{6}=0.5 \mathrm{~Hz}$. The original lowest pole frequency is 50 Hz , so the reduction in frequency is a factor of $10^{2}$, suggesting that $C_{N E W}=100 C_{\text {ORIG }}=100 \times 3.183 p F=318.3 p F$.
8. What is the actual (not approximate) phase margin using your new value for $\mathrm{C}_{\mathrm{F}}$ ?

At $1 / \beta_{F B}=40 \mathrm{~dB}$, the unity gain frequency is $f_{1}=500 \mathrm{kHz}$; at this frequency the phase is

$$
\begin{aligned}
\phi & =\left\{\tan ^{-1}\left(f_{1} / f_{P_{1}}\right)+\tan ^{-1}\left(f_{1} / f_{P_{2}}\right)+\tan ^{-1}\left(f_{1} / f_{P_{3}}\right)\right\} \\
& \approx-\left\{90^{\circ}+45^{\circ}+\tan ^{-1}(500 \mathrm{k} / 2.5 \mathrm{M})\right\}=-135^{\circ}-11.3^{\circ}=-146.3^{\circ}
\end{aligned}
$$

Therefore, the phase margin is $\phi_{M}=-146.3^{\circ}+180^{\circ}=33.7^{\circ}$.


[^0]:    ${ }^{1}$ For example, $C_{L}$ could be the $C_{\pi}$ of the input transistor of the following stage.

